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**ON A BOUNDARY VALUE PROBLEM FOR
SINGULARLY PERTURBED QUASILINEAR
ELLIPTIC EQUATION IN CURVILINEAR
TRAPEZOID**

Abstract

A boundary value problem for an elliptic type quasilinear equation of second order containing a small parameter for higher derivatives is considered in a curvilinear trapezoid. Asymptotic expansion of generalized solution of the considered problem is constructed to within any power of small parameter and remainder term is estimated.

Let $x = \varphi_1(y)$, $x = \varphi_2(y)$ be sufficiently smooth functions determined in $[a, b]$ and satisfy the following conditions:

- I. $\varphi_1(y) < \varphi_2(y)$ for $y \in [a, b]$;
- II. $\varphi_1(y) < y$ for $y \in [a, b]$, $\varphi_2(y) > y$, $y \in [a, b]$;
- III. $\varphi_1(a) = a$, $\varphi_2(b) = b$
- IV. $\varphi_1'(y) < 1$, $\varphi_2'(y) < 1$ for $y \in [a, b]$.

Introduce the denotation:

$$\Gamma_1 = \{(x, y) | x = \varphi_1(y), a \leq y \leq b\}, \quad \Gamma_2 = \{(x, y) | \varphi_1(y) \leq x \leq \varphi_2(y), y = b\},$$

$$\Gamma_3 = \{(x, y) | x = \varphi_2(y), a \leq y \leq b\}, \quad \Gamma_4 = \{(x, y) | \varphi_1(y) \leq x \leq \varphi_2(y), y = a\}.$$

In $\Omega = \{(x, y) | \varphi_1(y) \leq x \leq \varphi_2(y), a \leq y \leq b\}$ we consider the following boundary value problem

$$L_\varepsilon U \equiv -\varepsilon^p \left[\frac{\partial}{\partial x} \left(\frac{\partial U}{\partial x} \right)^p + \frac{\partial}{\partial y} \left(\frac{\partial U}{\partial y} \right)^p \right] -$$

$$-\varepsilon \Delta U + \frac{\partial U}{\partial x} + \frac{\partial U}{\partial y} + F(x, y, U) = 0, \quad (1)$$

$$U|_\Gamma = 0, \quad (2)$$

where $\varepsilon > 0$ is a small parameter, $p = 2k + 1$, k is an arbitrary natural number, $\Gamma = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3 \cup \Gamma_4$, $F(x, y, U)$ is a given smooth function satisfying the condition

$$\frac{\partial F(x, y, U)}{\partial U} \geq \gamma^2 > 0 \quad \text{for } (x, y, U) \in (\Omega \setminus \{(x, y) \in \Omega | x = y\}) \times (-\infty, +\infty). \quad (3)$$

It is assumed that $F(x, y, U)$ may depend on U both linearly, i.e. $F(x, y, U) = d(x, y)U - f(x, y)$, $d(x, y) \geq \gamma^2 > 0$ and non-linearly.

It is known that for each fixed ε there exists a unique generalized solution of problem (1),(2) in space $\overset{\circ}{W}_{p+1}^1(\Omega)$. Obviously, if $F(x, y, 0) \equiv 0$, the problem (1),(2) has only a trivial solution. Therefore, assume that

$$F(x, y, 0) \not\equiv 0 \quad \text{for } (x, y) \in \Omega. \quad (4)$$

Asymptotics of the solution of boundary value problem for a second order quasi-linear elliptic equation in n -dimensional bounded domain with smooth boundary is constructed in the paper [1]. In the paper [2], a boundary value problem is investigated for equation (1) in a rectangular domain.

Our goal is to construct asymptotic expansion of the solution of boundary value problem (1),(2) in small parameter $\varepsilon > 0$.

In the connection, we'll conduct iteration processes.

In the first iteration process, approximate solution of the equation is sought in the form

$$W = W_0 + \varepsilon W_1 + \dots + \varepsilon^n W_n, \quad (5)$$

and the functions $W_i(x, y); i = 0, 1, \dots, n$ will be chosen so that

$$L_\varepsilon W = 0 \quad (\varepsilon^{n+1}). \quad (6)$$

From (1),(5) and (6) we get the following equations:

$$\frac{\partial W_0}{\partial x} + \frac{\partial W_0}{\partial y} + F(x, y, W_0) = 0, \quad (7)$$

$$\frac{\partial W_i}{\partial x} + \frac{\partial W_i}{\partial y} + \frac{\partial F(x, y, W_0)}{\partial W_0} W_i = f_i; \quad i = 1, 2, \dots, n, \quad (8)$$

where the functions f_i depend on W_0, W_1, \dots, W_{i-1} and their derivatives. Boundary conditions on the lines Γ_1, Γ_4 that are parts of the boundary Γ of domain Ω will be used for equations (7),(8). Then boundary condition (2) may not be fulfilled on the lines Γ_2 and Γ_3 . The boundary layer type functions should be constructed near Γ_2 and Γ_3 in order to compensate, the lost boundary conditions.

As it was noted above, we'll solve equations (7),(8) under the following boundary conditions:

$$\begin{aligned} W_i|_{x=\varphi_1(y)} &= 0, \quad (a \leq y \leq b); \\ W_i|_{y=a} &= 0, \quad (\varphi_1(a) \leq x \leq \varphi_2(a)); \quad i = 0, 1, \dots, n. \end{aligned} \quad (9)$$

Problem (7),(9) (for $i = 0$) will be called a degenerated problem corresponding to problem (1),(2).

It holds the following

Theorem 1. Let $F(x, y, U) \in C^m(\Omega \times (-\infty, +\infty))$, the function $F(x, y, U)$ satisfy conditions (3),(4) and the condition

$$\left. \frac{\partial^i f(x, y)}{\partial x^{i_1} \partial y^{i_2}} \right|_{x=y} = 0; \quad y \in [a, b], \quad i = i_1 + i_2; \quad i = 0, 1, \dots, m, \quad (10)$$

where $x_1 = \psi(y_1)$ is a solution of the equation $x_1 = \varphi_1(x_1 + y_1)$ with respect to x_1 . Using formula (17), it is easily proved that if condition (10) is fulfilled, then $W_0(x, y) \in C^m(\Omega)$ and condition (13) is satisfied.

In the case of nonlinear dependence of $F(x, y, W_0)$ on W_0 , the problems (15),(16) are reduced to the following Cauchy problems for ordinary differential equations:

$$\frac{dW_0^{(1)}}{dx_1} = -F(x_1, x_1 + y_1, W_0^{(1)}), \quad W_0^{(1)} \Big|_{x_1=\psi(y_1)} = 0, \quad (18)$$

$$\frac{dW_0^{(2)}}{dy_1} = -F(x_1 + y_1, y_1, W_0^{(2)}), \quad W_0^{(2)} \Big|_{y_1=a} = 0. \quad (19)$$

Existence of local solutions of problems (18), (19) is obvious. Using condition (3), we can get a priori estimations for these local solutions. Possibility of continuous continuation of local solutions on Ω_1 and Ω_2 follows from the obtained a priori estimations.

In order to study differential properties of the solution of the degenerate problem, in the non-linear case we reduce this problem to the following non-linear integral equations:

$$W_0(x, y) = \begin{cases} - \int_{\psi(y_1)}^{x_1} F(\tau, \tau + y_1, W_0(\tau, \tau + y_1)) d\tau, \\ \quad x_1 = x, \quad y_1 = y - x, \quad y > x, \\ - \int_a^{y_1} F(x_1 + \tau, \tau, W_0(x_1 + \tau, \tau)) d\tau, \\ \quad x_1 = x - y, \quad y_1 = y, \quad x > y. \end{cases} \quad (20)$$

Using formula (20), we can prove that if conditions (11), (12) are satisfied, then $W_0(x, y) \in C^m(D)$ and (13) is satisfied. Theorem 1 is proved.

The problems (8), (9) for $i = 1, 2, \dots, n$ wherefrom the functions W_1, W_2, \dots, W_n will be successively determined, and linear. We can write the solutions of these problems in the obvious form by formula (17). Notice that the functions $W_i(x, y); i = 1, 2, \dots, n$ will also vanish for $y = x$ together with their own derivatives.

If in theorem 1 we take $m = 2n + 2$, then from this theorem in the case of linear dependence of $F(x, y, U)$ on U it follows that $W_i \in C^{2(n-i)+2}(\Omega); i = 0, 1, \dots, n$. Hence and from (5) we get $W \in C^2(\Omega)$ for each fixed value of $\varepsilon \in [0, \varepsilon_0]$. Consequently the operator L_ε may operate on the constructed function W .

Thus, we constructed the function W that is an approximate solution of equation (1) in the sense of (6) and satisfies the boundary conditions:

$$W|_{\Gamma_1} = 0, \quad W|_{\Gamma_4} = 0. \quad (21)$$

In order to construct a boundary layer function near the boundary Γ_3 , at first we should write a new decomposition of the operator L_3 near this line. Make change

of variables: $\varphi_2(y) - x = \varepsilon\tau$, $y = y_1$. Consider the auxiliary function

$$r = \sum_{j=0}^{n+1} \varepsilon^j r_j(\tau, y_1)$$

where $r_j(\tau, y_1)$ are some functions determined near the line $x = \varphi_2(y)$. Considering this change, substituting the expressions r in $L_\varepsilon r$, expanding the function $F(\varphi_2(y_1) - \varepsilon\tau, y_1, r)$ and other nonlinear members in power of ε , after certain transformations we get a new decomposition of the operator $L_\varepsilon r$ in the coordinates (τ, y_1) in the form

$$\begin{aligned} L_{\varepsilon,1} \equiv \varepsilon^{-1} \left\{ - \left[\delta_1^2(y_1) \frac{\partial}{\partial \tau} \left(\frac{\partial r_0}{\partial \tau} \right)^{2k+1} + \delta_2^2(y_1) \frac{\partial^2 r_0}{\partial \tau^2} + \delta_3^2(y_1) \frac{\partial^2 r_0}{\partial \tau} \right] + \right. \\ \left. + \sum_{j=1}^{n+1} \varepsilon^j \left[- (2k+1) \delta_1^2(y_1) \frac{\partial}{\partial \tau} \left(\left(\frac{\partial r_0}{\partial \tau} \right)^{2k} \frac{\partial r_j}{\partial \tau} \right) - \delta_2^2(y_1) \frac{\partial^2 r_j}{\partial \tau^2} - \delta_3^2(y_1) \frac{\partial r_j}{\partial \tau} + \right. \right. \\ \left. \left. + h_j(r_0, r_1, \dots, r_{j-1}) \right] + 0(\varepsilon^{n+2}) \right\}. \end{aligned} \quad (22)$$

Here h_j , are the known functions dependent on $\tau, y_1, r_0, r_1, \dots, r_{j-1}$ and their first and second derivatives. The functions $\delta_1^2(y_1), \delta_2^2(y_1), \delta_3^2(y_1)$ are determined by the following formulae:

$$\delta_1^2(y_1) = 1 + [\varphi_2'(y_1)]^{2k+2}, \quad \delta_2^2(y_1) = [1 + \varphi_2'(y_1)]^2, \quad \delta_3^2(y_1) = 1 - \varphi_2'(y_1).$$

We'll look for a boundary layer type function near the boundary Γ_3 in the form

$$V = V_0(\tau, y_1) + \varepsilon V_1(\tau, y_1) + \dots + \varepsilon^{n+1} V_{n+1}(\tau, y_1), \quad (23)$$

as a solution of the equation

$$L_{\varepsilon,1}(w + V) - L_{\varepsilon,1}W = 0(\varepsilon^{n+1}). \quad (24)$$

Before we substitute expressions (5), (23) in (24), we should expand each function $W_i(\varphi_2(y_1) - \varepsilon\tau, y_1)$ by Taylor formula at the point $(\varphi_2(y_1), y_1)$ and get a new expansion in powers of ε of the function W in the coordinates (τ, y_1) . A new expansion of the function W is of the form

$$W = \sum_{j=0}^{n+1} \varepsilon^j \omega_j(\tau, y_1) + 0(\varepsilon^{n+2}), \quad (25)$$

where $\omega_0(\tau, y_1) = W_0(\varphi_2(y_1), y_1)$ is independent on τ , the remaining functions ω_k are determined by the formula

$$\omega_k = \sum_{i+j=k} \frac{(-1)^i}{i!} \frac{\partial^i W_j(\varphi_2(y_1), y_1)}{\partial x^i} \tau^i; \quad k = 1, 2, \dots, n+1.$$

It follows from (22) – (25) that the functions V_j contained in the right hand side of (23) are the solutions of the following equations:

$$\delta_1^2(y_1) \frac{\partial}{\partial \tau} \left(\frac{\partial V_0}{\partial \tau} \right)^{2k+1} + \delta_2^2(y_1) \frac{\partial^2 V_0}{\partial \tau^2} + \delta_3^2(y_1) \frac{\partial V_0}{\partial \tau} = 0, \quad (26)$$

$$\frac{\partial}{\partial \tau} \left\{ \left[(2k+1) \delta_1^2(y_1) \left(\frac{\partial V_0}{\partial \tau} \right)^{2k} + \delta_2^2(y_1) \right] \frac{\partial V_j}{\partial \tau} \right\} +$$

$$+ \delta_3^2(y_1) \frac{\partial V_j}{\partial \tau} = H_j(\tau, y_1) \quad (27)$$

where H_j ; $j = 1, 2, \dots, n+1$ are the known functions dependent on $\tau, y_1, V_0, V_1, \dots, V_{j-1}, \omega_0, \omega_1, \dots, \omega_j$ and their first and second derivatives.

Boundary conditions for equations (26), (27) are obtained from the requirement that the sum $W + V$ should satisfy the boundary condition

$$(W + V)|_{\Gamma_3} = 0 \quad (28)$$

Substituting the expressions for W and V from (5) and (23), respectively to (28) and considering also the fact that we look for $V_j, j = 0, 1, \dots, n+1$ as a boundary layer type function, we have

$$V_0|_{\tau=0} = g_0(y_1), \quad \lim_{\tau \rightarrow +\infty} V_0 = 0, \quad (29)$$

$$V_j|_{\tau=0} = g_j(y_1), \quad \lim_{\tau \rightarrow +\infty} V_j = 0, \quad j = 1, 2, \dots, n+1 \quad (30)$$

where $g_i(y_1) = -W_i(\varphi_2(y_1), y_1)$ for $i = 0, 1, \dots, n$; $g_{n+1}(y_1) \equiv 0$.

The following theorem is true.

Theorem 2. *For each fixed $y_1 \in [a, b]$, problem (26), (29) has a unique solution which is differentiable with respect to τ and has continuous derivatives up to $(2n+2)$ -th order inclusively with respect to y_1 , and the function $V_0(\tau, y_1)$ and its derivatives exponentially tend to zero as $\tau \rightarrow +\infty$.*

Proof. At first we prove uniqueness of the solution of problem (26), (29).

If $V_0^{(1)}(\tau, y_1), V_0^{(2)}(\tau, y_2)$ are two solutions of problem (26), (29), we integrate by parts and get

$$\delta_1^2(y_1) \int_0^{+\infty} \left(\frac{\partial V_0^{(1)}}{\partial \tau} - \frac{\partial V_0^{(2)}}{\partial \tau} \right)^{2k+1} d\tau + 2^{2k+2} \delta_1^2(y_1) \int_0^{+\infty} \left(\frac{\partial V_0^{(1)}}{\partial \tau} - \frac{\partial V_0^{(2)}}{\partial \tau} \right)^2 d\tau \leq 0,$$

hence $V_0^{(1)}(\tau, y) \equiv V_0^{(2)}(\tau, y)$ follows.

Passing to the proof of the existence of the solution of problem (26), (29), we note that the variable y_1 plays as a parameter in this problem. Since $W_0(\varphi_2(a), a) = W_0(\varphi_2(b), b) = 0$, then for $y_1 = a$ and $y_1 = b$ the function $V_0 \equiv 0$ will satisfy problem (26), (29). It follows from uniqueness of the solution of the problem that in

the cases $y_1 = a$ and $y_1 = b$ the solution of problem (26), (29) is predetermined by an identity zero.

We should prove the existence of the solution of problem (26), (29) for $y_1 \in (a, b)$.

In a similar way as it was made in [3], we can prove that for each $y_1 \in (a, b)$ the solution of problem (26), (29) in parametric form has the view:

$$\tau = \frac{2k + 1}{2k} \frac{\delta_1^2(y_1)}{\delta_3^2(y_1)} (t_0^{2k} - t^{2k}) + \frac{\delta_2^2(y_1)}{\delta_3^2(y_1)} \ln \left| \frac{t_0}{t} \right|, \quad (31)$$

$$V_0 = -\frac{\delta_1^2(y_1)}{\delta_3^2(y_1)} t^{2k+1} - \frac{\delta_2^2(y_1)}{\delta_3^2(y_1)} t. \quad (32)$$

Here t is a parameter, $t_0(y_1)$ is a unique real root of the algebraic equation

$$t_0^{2k+1} + t_0 + g_0(y_1) = 0. \quad (33)$$

Using the obvious form of the solution of V_0 , we can prove that the function V_0 is infinitely differentiable with respect to τ and the estimation

$$\left| \frac{\partial^k V_0}{\partial \tau^k} \right| \leq c \exp \left[-\frac{\delta_2^2(y_1)}{\delta_3^2(y_1)} \tau \right], (c > 0); k = 0, 1, \dots \quad (34)$$

is valid for all $y_1 \in [a, b]$.

Investigate the behavior of $V_0(\tau, y_1)$ with respect to y_1 . At first, note that as equation (33) has a unique real root $t_0(g_0(y_1))$ for all $y_1 \in [a, b]$ and the function $g_0(y_1) \in C^{2n+2}[a, b]$, then the function $t_0(g_0(y_1))$ also will have continuous derivatives up to $(2n + 2)$ order inclusively. Hence and from (31), (32) the smoothness of the function $V_0(\tau, y_1)$ with respect y_1 follows.

Now estimate as $\tau \rightarrow +\infty$ the derivatives with respect to y_1 of the function $V_0(\tau, y_1)$.

The function $z = \frac{\partial V_0}{\partial y_1}$ satisfies the equation in variations that is obtained from equation (26) by differentiating with respect to y_1 :

$$\frac{\partial}{\partial \tau} \left[A(\tau, y_1) \frac{\partial z}{\partial \tau} \right] + \delta_3^2(y_1) \frac{\partial z}{\partial \tau} = \Phi_1 \quad (35)$$

where

$$A(\tau, y_1) = (2k + 1) \delta_1^2(y_1) \left(\frac{\partial V_0}{\partial \tau} \right)^{2k} + \delta_2^2(y_1), \quad (36)$$

$$\Phi_1(\tau, y_1) = -[\delta_1^2(y_1)]' \frac{\partial}{\partial \tau} \left(\frac{\partial V_0}{\partial \tau} \right)^{2k+1} - [\delta_2^2(y_1)]' \frac{\partial^2 V_0}{\partial \tau^2} - [\delta_3^2(y_1)]' \frac{\partial V_0}{\partial \tau}. \quad (37)$$

Obviously, the function z should satisfy the boundary conditions:

$$z|_{\tau=0} = g_0'(y_1), \quad \lim_{\tau \rightarrow +\infty} z = 0. \quad (38)$$

The solution of problem (35), (38) is of the form

$$z = \left\{ \int_0^\tau \Phi_2(\xi_1, y_1) \exp \left[\delta_3^2(y_1) \int_0^{\xi_1} \frac{d\xi}{A(\xi, y_1)} \right] d\xi_1 + \right. \\ \left. + g'_0(y_1) \right\} \exp \left[-\delta_3^2(y_1) \int_0^\tau \frac{d\xi}{A(\xi, y_1)} \right], \quad (39)$$

where

$$\Phi_2(\tau, y_1) = -\frac{1}{A(\tau, y_1)} \int_\tau^\infty \Phi_1(\xi, y_1) d\xi. \quad (40)$$

Using (36), (37), (39), (40) and estimation (34), from (39) we can get the following estimations:

$$|z| = \left| \frac{\partial V_0}{\partial y_1} \right| \leq (C + C_2\tau) \exp(-\tau) \quad \text{for } \delta_3^2(y_1) = \delta_2^2(y_1), \quad (41)$$

$$|z| = \left| \frac{\partial V_0}{\partial y_1} \right| \leq C_3 \exp \left[-\frac{\delta_2^2(y_1)}{\delta_3^2(y_1)} \tau \right] + \\ + C_4 \exp \left[-\frac{\delta_3^2(y_1)}{\delta_2^2(y_1)} \tau \right] \quad \text{for } \delta_3^2(y_1) \neq \delta_2^2(y_1), \quad (42)$$

where C_1, C_2, C_3, C_4 are positive constants.

We can establish estimations for the next derivatives of V_0 with respect to y_1 and for mixed derivatives in a similar way. Theorem 2 is proved.

Now construct the functions V_1, V_2, \dots, V_{n+1} that are the solutions of equations (27) satisfying boundary conditions (30) for $j = 1, 2, \dots, n+1$. Equations (27) and (35) differ only by the right hand sides. Therefore, the functions $V_j; j = 1, 2, \dots, n+1$ will also be determined by formula (39), only changing the functions $\Phi_2(\xi_1, y_1)$, $g'_0(y_1)$ by another appropriate functions. Using the obvious forms of the right hand sides of equations (27), we can prove validity of the estimation of the form

$$\left| \frac{\partial^k V_j(\tau, y_1)}{\partial \tau^{k_1} \partial y^{k_2}} \right| \leq \left(\sum_{i=0}^{j+1} C_i \tau^i \right) \exp(-\tau) \quad \text{for } \delta_3^2(y_1) = \delta_2^2(y_1), \quad (43)$$

$$\left| \frac{\partial^k V_j(\tau, y_1)}{\partial \tau^{k_1} \partial y^{k_2}} \right| \leq \left(\sum_{i=0}^j C_i^{(1)} \tau^i \right) \exp \left[-\frac{\delta_2^2(y_1)}{\delta_3^2(y_1)} \tau \right] + \\ + \left(\sum_{i=0}^j C_i^{(2)} \tau^i \right) \exp \left[-\frac{\delta_3^2(y_1)}{\delta_2^2(y_1)} \tau \right] \quad \text{for } \delta_3^2(y_1) \neq \delta_2^2(y_1), \quad (44)$$

where $k = k_1 + k_2$, $k_2 + 2(j-1) = 2n+2$; $j = 1, 2, \dots, n+1$; $C_i, C_i^{(1)}, C_i^{(2)}$ are positive constants.

Multiply all the functions by $V_j; j = 1, 2, \dots, n + 1$ a by smoothing multiplier and leave previous denotation for obtained new functions. Note that at the expense of smoothing functions, V doesn't violate fulfilment of the first condition from (21), i.e. the sum $W + V$, in addition to condition (28), satisfies the condition

$$(W + V)|_{\Gamma_1} = 0. \tag{45}$$

But the function V may violate fulfilment of the second condition from (21) for the sum $W + V$. In order the condition

$$(W + V)|_{\Gamma_4} = 0, \tag{46}$$

be fulfilled, all the functions V_j for $y = a$ should vanish, i.e.

$$V_j|_{y=a} = 0; j = 0, 1, \dots, n + 1. \tag{47}$$

Obviously, condition (47) is fulfilled for $j = 0$. Assume that the function $F(x, y, U)$ satisfies the condition

$$\frac{\partial^k f(\varphi_2(a), a)}{\partial x^{k_1} \partial y^{k_2}} = 0; k = k_1 + k_2; k = 0, 1, \dots, 2n + 1, \tag{48}$$

in the case of linear dependence of F on U , the condition

$$\frac{\partial^k F(\varphi_2(a), a, 0)}{\partial x^{k_1} \partial y^{k_2} \partial U^k} = 0; k = k_1 + k_2 + k_3; k = 0, 1, \dots, 2n + 1, \tag{49}$$

in the case of nonlinear dependence of F on U . Then condition (47) will be fulfilled for all $j = 1, 2, \dots, n + 1$.

Thus, the constructed sum $W + V$ will satisfy the boundary conditions (28), (45), (46). But generally speaking, this sum doesn't satisfy the homogeneous boundary condition on Γ_2 . Therefore, it is necessary to construct the boundary layer type function

$$\eta = \eta_0 + \varepsilon \eta_1 + \dots + \varepsilon^{n+1} \eta_{n+1}, \tag{50}$$

near the boundary Γ_2 that should satisfy the fulfilment of the boundary condition

$$(W + V + \eta)|_{\Gamma_2} = 0, \tag{51}$$

Therewith, the equations whence the functions $\eta_j; j = 0, 1, \dots, n + 1$ are determined, are obtained from the equality

$$L_{\varepsilon,2}(W + V + \eta) - L_{\varepsilon,2}(W + V) = 0(\varepsilon^{n+1}), \tag{52}$$

where $L_{\varepsilon,2}$ is another decomposition of the operator L_ε near the boundary Γ_2 .

Here, change of variables near the boundary Γ_2 is conducted by the formula: $x = x, b - y = \varepsilon \xi$. Expanding each function $W_i(x, b - \varepsilon \xi)$ and $V_i(\tau, b - \varepsilon \xi)$ by

Taylor formula at the points (x, b) and (τ, b) , from (52) we obtain the following equations:

$$\frac{\partial}{\partial \xi} \left(\frac{\partial \eta_0}{\partial \xi} \right)^{2k+1} + \frac{\partial^2 \eta_0}{\partial \xi^2} + \frac{\partial \eta_0}{\partial \xi} = 0,$$

$$\frac{\partial}{\partial \xi} \left\{ \left[\left(\frac{\partial \eta_0}{\partial \xi} \right)^{2k+1} + 1 \right] \frac{\partial \eta_j}{\partial \xi} \right\} + \frac{\partial \eta_j}{\partial \xi} = G_j,$$

where $G_j; j = 1, 2, \dots, n + 1$ are the known functions.

Comparison of obtained equations with equations (26), (27) shows that the construction of the function η_j in the right hand side of (50) will very little differ from the procedure on finding the functions $V_j; j = 0, 1, \dots, n + 1$. Therefore, we'll not stop on constructions of η_j :

Multiply all the functions by $\eta_0, \eta_1, \dots, \eta_{n+1}$ by the smoothing functions. At the expense of smoothing multipliers the functions η_j vanish on Γ_4 . Therefore, in addition to condition (51) the sum $W + V + \eta$ satisfies the condition

$$(W + V + \eta)|_{\Gamma_4} = 0. \tag{53}$$

Using the conversion to zero of the functions $W_i(x, y); i = 0, 1, \dots, n$ and their derivatives for $x = \varphi_2(b), y = b$, we can prove

$$\eta_j|_{x=\varphi_2(y)} = 0; j = 0, 1, \dots, n + 1.$$

Hence and from (28) it follows that the sum $W + V + \eta$ satisfies also the boundary condition

$$(W + V + \eta)|_{\Gamma_3} = 0, \tag{54}$$

Assume that the function $F(x, y, U)$ satisfies the condition

$$\frac{\partial^k f(\varphi_1(b), b)}{\partial x^{k_1} \partial y^{k_2}} = 0; k = k_1 + k_2; k = 0, 1, \dots, 2n + 1, \tag{55}$$

when the function F linearly depends on U , the condition

$$\frac{\partial^k F(\varphi_1(b), b, 0)}{\partial x^{k_1} \partial y^{k_2} \partial U^{k_3}} = 0; k = k_1 + k_2 + k_3; k = 0, 1, \dots, 2n + 1. \tag{56}$$

when F nonlinearly depends on U . Then along with boundary conditions (51), (53), (54) the sum $W + V + \eta$ will also satisfy the boundary condition

$$(W + V + \eta)|_{\Gamma_1} = 0. \tag{57}$$

Thus, we constructed the sum $\tilde{U} = U + V + \eta$ that following (51), (53), (54), (57) satisfies the boundary condition

$$\tilde{U}|_{\Gamma} = 0. \tag{58}$$

Summing up (6), (24), (52) we have that \tilde{U} satisfies the equation

$$L_\varepsilon \tilde{U} = 0 (\varepsilon^{n+1}). \tag{59}$$

Having denoted $U - \tilde{U} = z$, we get the following asymptotic expansion in small parameter of the solution of problem (1), (2) :

$$U = \sum_{i=0}^n \varepsilon^i W_i + \sum_{i=0}^{n+1} \varepsilon^j V_i + \sum_{i=0}^{n+1} \varepsilon^j \eta_j + z, \quad (60)$$

where z is a remainder term.

It follows from (2) and (58) that the remainder term z satisfies the boundary condition

$$z|_{\Gamma} = 0. \quad (61)$$

Subtracting (59) from (1), multiplying the both hand sides of the obtained equality by $z = U - \tilde{U}$ and integrating the obtained expressions on domain Ω , allowing for condition (61), after certain transformations we get the estimation

$$\begin{aligned} \varepsilon^p \iint_{\Omega} \left[\left(\frac{\partial z}{\partial x} \right)^{p+1} + \left(\frac{\partial z}{\partial y} \right)^{p+1} \right] dx dy + \varepsilon \iint_{\Omega} \left[\left(\frac{\partial z}{\partial x} \right)^2 + \left(\frac{\partial z}{\partial y} \right)^2 \right] dx dy + \\ + C_1 \iint_{\Omega} z^2 dx dy \leq C_2 \varepsilon^{2(n+1)}, \end{aligned} \quad (62)$$

where $C_1 > 0, C_2 > 0$ are the constants independent of ε .

Combining the results obtained above, we arrive at the following statement.

Theorem 3. Assume $F(x, y, U) \in C^{2(n+1)}(\Omega \times (-\infty, \infty))$, the conditions (3), (4) and conditions (10), (48), (55) are fulfilled in the case of linear dependence of F on U , the conditions (11), (12), (49), (56) in the case of nonlinear dependence of F on U . Then for generalized solution of problem (1), (2) it is valid asymptotic representation (60), where the functions W_i are determined by the first iteration process, V_j, η_j are the boundary layer type functions near the boundaries Γ_3, Γ_2 that are determined by appropriate iteration processes, z is a remainder term and estimation (62) is valid for it.

Remark. We can reject from conditions III imposed on $\varphi_1(y), \varphi_2(y)$. Then instead of conditions (10) – (12) for $y = x$, appropriate conditions for $y = x + \varphi_1(a) - a$ should be taken.

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